Unit-1 Divide and Conquer

- Dr. K.RAGHAVA RAO
 - Professor in CSE
 - KL University
 - krraocse@gmail.com
- http://mcadaa.blog.com

Divide-and-Conquer

- Divide the problem into a number of subproblems.
- •Conquer the subproblems by solving them recursively. If the
- subproblem sizes are small enough, solve the subproblems in a
- straightforward manner.

Divide-and-Conquer

• Combine the solutions to the subproblems into the

solution for the original problem.

Merge Sort Algorithm

Divide: Divide the n-element sequence into two

subsequences of n/2 elements each.

Conquer: Sort the two subsequences recursively using

merge sort.

Combine: Merge the two sorted sequences.

How to merge two sorted sequences

•We have two subarrays A[p..q] and A[q+1..r] in sorted

order.

• Merge sort algorithm merges them to form a single

sorted subarray that replaces the current subarray A[p..r]

To sort the entire sequence A[1 .. n], make the initial call to the procedure MERGE-SORT (A, 1, n).

```
MERGE-SORT (A, p, r){
```

```
1. IF p < r
```

```
2. THEN q = FLOOR[(p + r)/2]
```

```
3. MERGESORT (A, p, q)
```

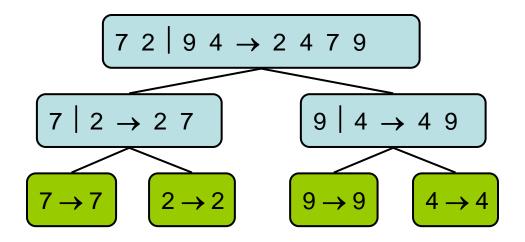
```
4. MERGE SORT(A, q + 1, r)
```

```
5. MERGE (A, p, q, r) // Conquer step. }
```

// Check for base case // Divide step // Conquer step. // Conquer step. The **pseudocode** of the MERGE procedure is as follow:

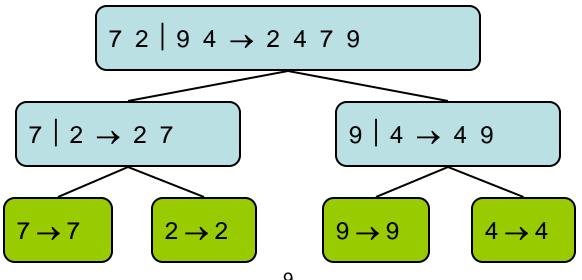
```
MERGE (A, p, q, r)
1. n_1 \leftarrow q - p + 1
2. n_2 \leftarrow r - q
3. Create arrays L[1 . . n_1 + 1] and R[1 . . . n_1 + 1]
. n_2 + 1]
4. FOR i \leftarrow 1 TO n_1
           DO L[i] \leftarrow A[p + i - 1]
5.
6. FOR j \leftarrow 1 TO n_2
7. DO R[i] \leftarrow A[q+i]
8. L[n_1 + 1] \leftarrow \infty
9. R[n_2 + 1] \leftarrow \infty
10. i ← 1
11. j ← 1
12. FOR k \leftarrow p TO r
          DO IF L[i] \leq R[j]
13.
14.
                THEN A[k] \leftarrow L[i]
15.
                     i \leftarrow i + 1
               ELSE A[k] \leftarrow R[j]
16.
                     j ← j + 1
17.
```

Merge Sort



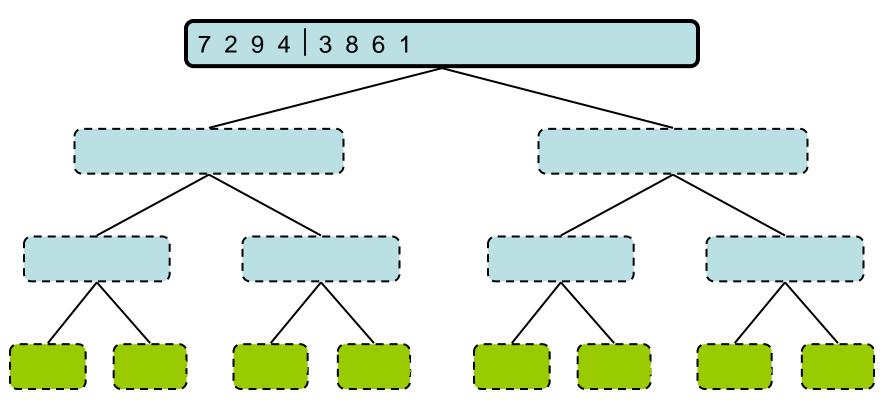
Merge-Sort Tree

- An execution of merge-sort is depicted by a binary tree
 - each node represents a recursive call of merge-sort and stores
 - unsorted sequence before the execution and its partition
 - sorted sequence at the end of the execution
 - the root is the initial call
 - the leaves are calls on subsequences of size 0 or 1

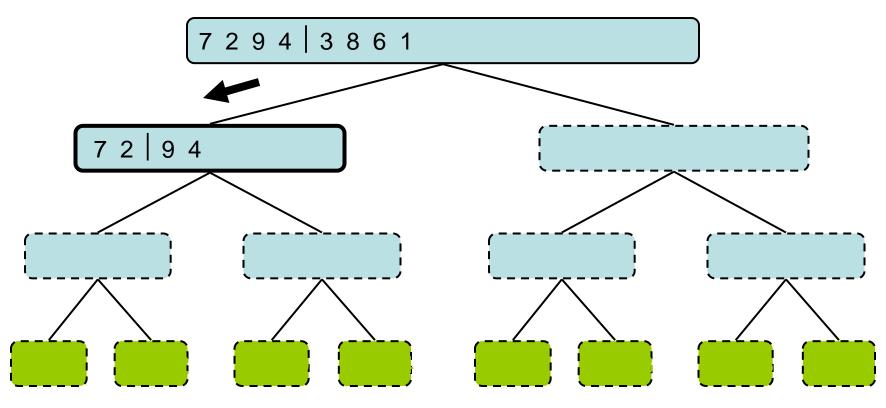


Execution Example

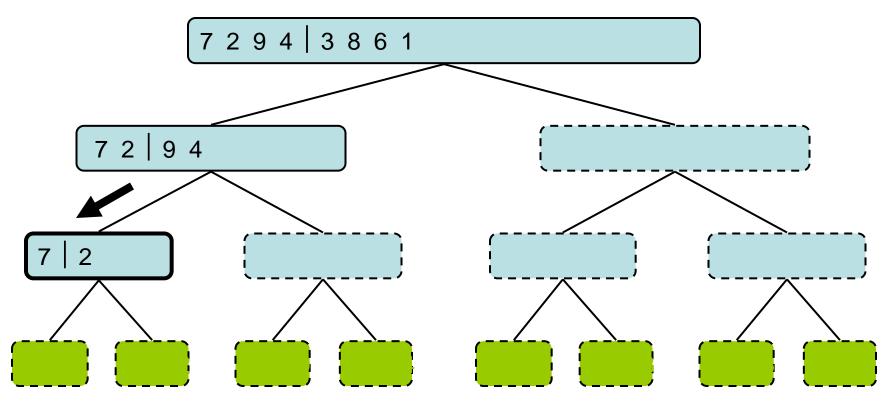
Partition



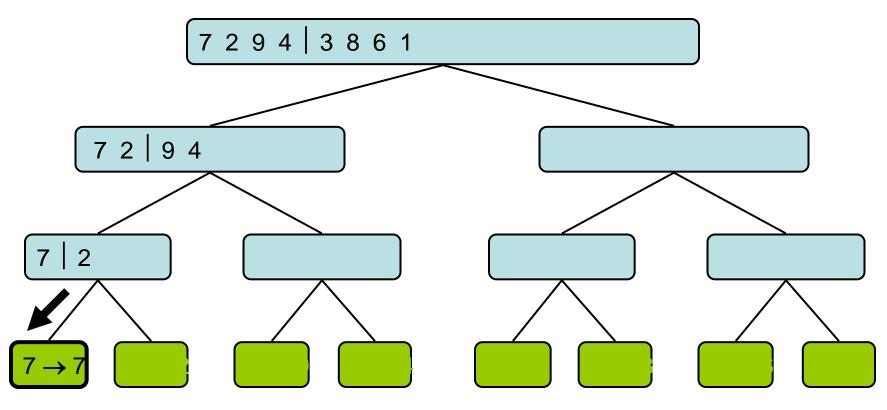
• Recursive call, partition



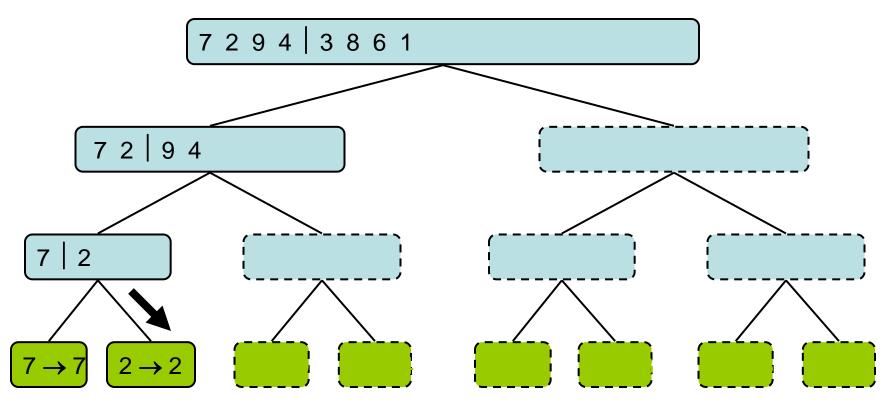
• Recursive call, partition



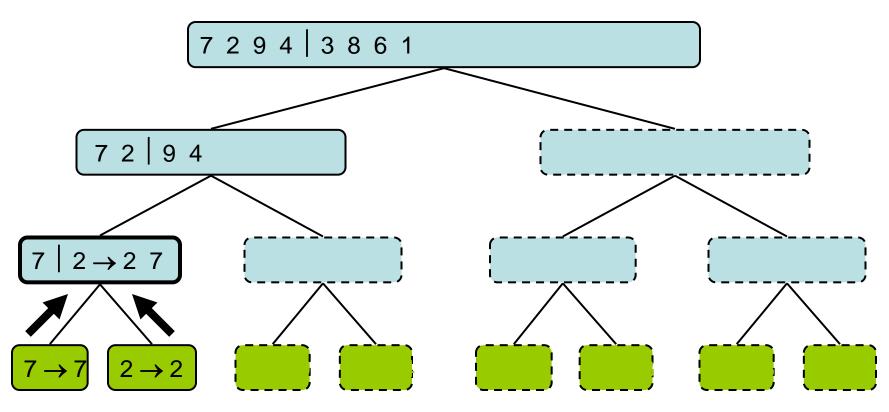
• Recursive call, base case



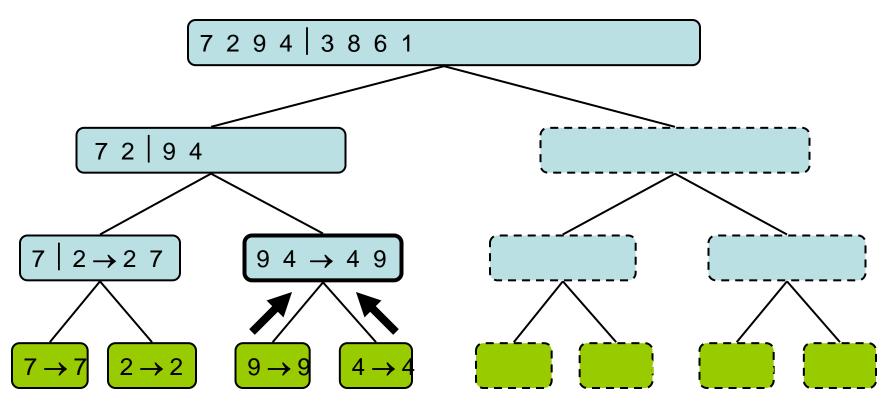
• Recursive call, base case



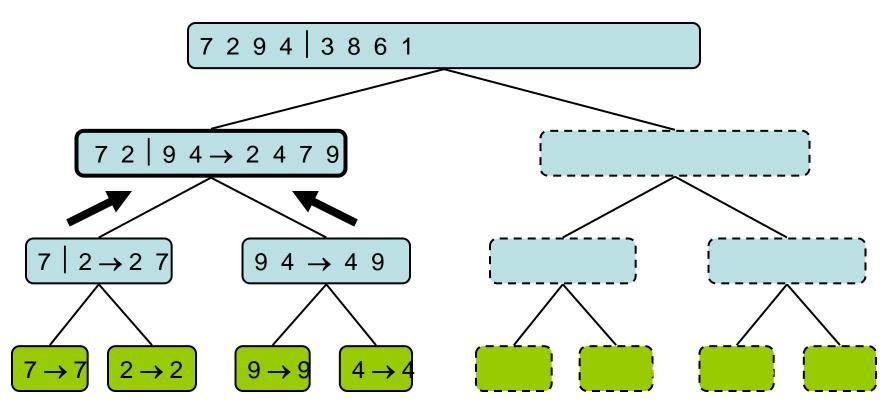
• Merge



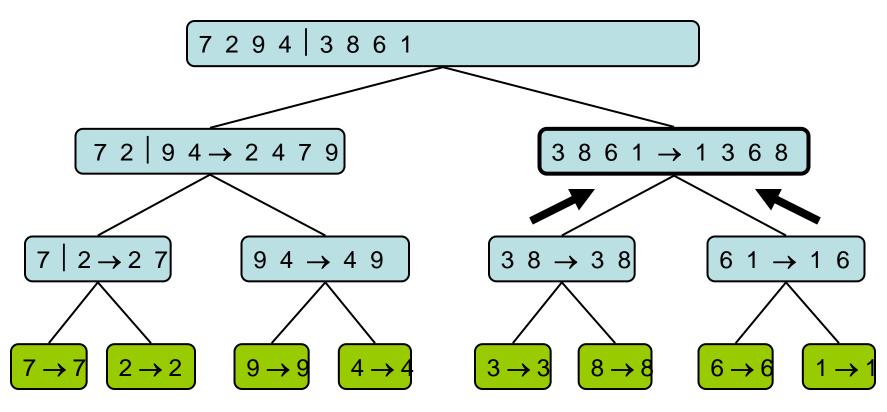
• Recursive call, ..., base case, merge



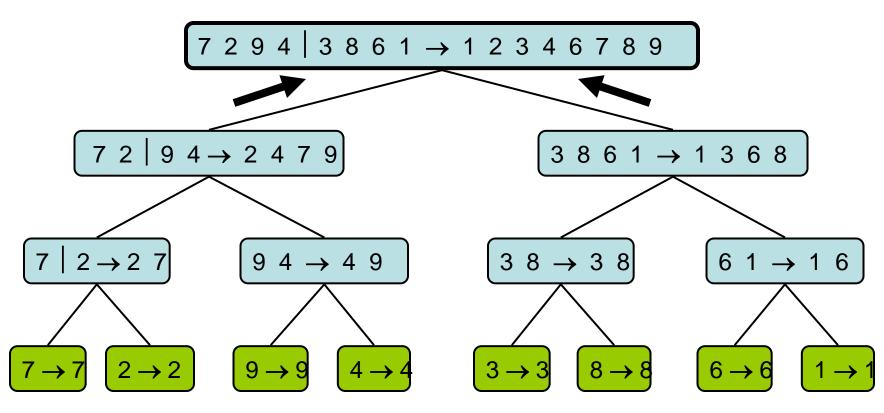
• Merge



• Recursive call, ..., merge, merge



• Merge



Merge Sort

Analyzing Divide-and-Conquer Algorithm

When an algorithm contains a recursive call to

itself, its running time can be described by a

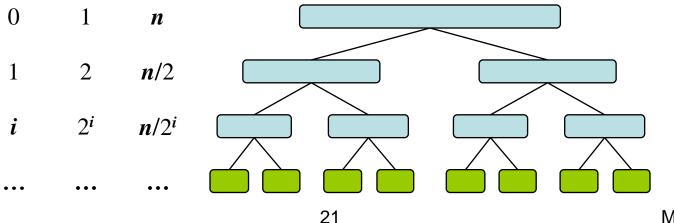
recurrence equation or recurrence which

describes the running time

Analysis of Merge-Sort

- The height h of the merge-sort tree is $O(\log n)$
 - at each recursive call we divide in half the sequence,
- The overall amount or work done at the nodes of depth i is O(n)
 - we partition and merge 2^i sequences of size $n/2^i$
 - we make 2^{i+1} recursive calls
- Thus, the total running time of merge-sort is $O(n \log n)$

depth #seqs size



If the problem size is small enough, say

n<=c for some constant c, the

straightforward solution takes constant

time, can be written as $\theta(1)$.

If we have a subproblems, each of which is

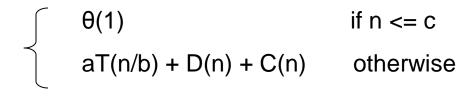
1/b the size of the original. D(n) time to

divide the problem and C(n) time to

combine the solution.

The recurrence

T(n)=





Divide: The divide step computes the

middle of the subarray which takes

constant time, $D(n)=\theta(1)$

Conquer: We recursively solve two

subproblems, each of size n/2, which

contributes 2T(n/2) to the running time.



Combine: Merge procedure takes $\theta(n)$ time

on an n-element subarray. $C(n)=\theta(n)$

The recurrence

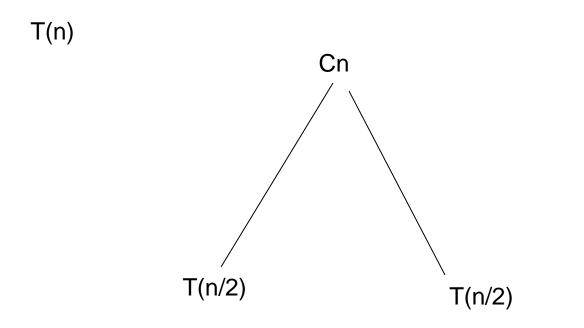
$$\mathbf{T(n)} = \begin{cases} \theta(1) & \text{if } n=1 \\ 2T(n/2) + \theta(n) & \text{if } n>1 \end{cases}$$

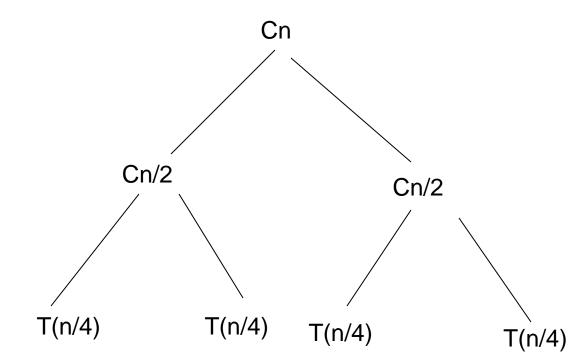
Let us rewrite the recurrence

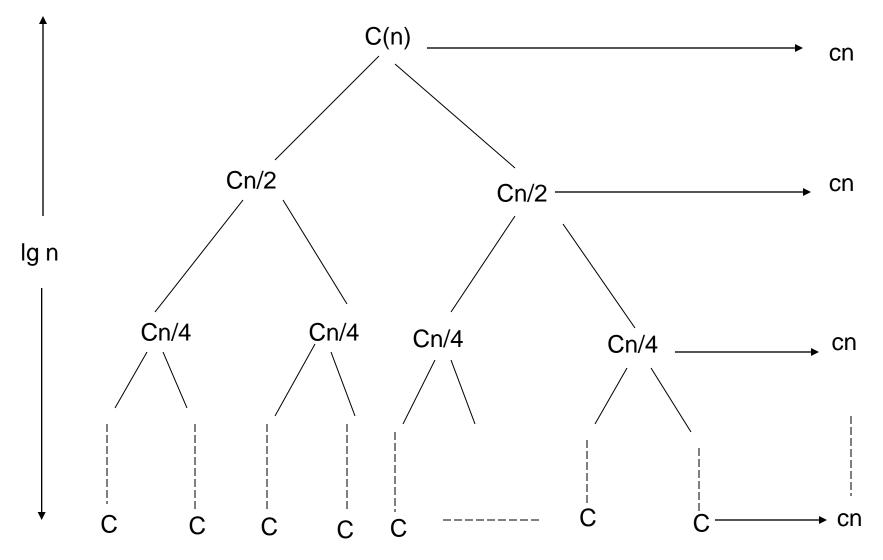
 $T(n) = \begin{cases} C & \text{if } n=1 \\ 2T(n/2) + cn & \text{if } n>1 \end{cases}$

C represents the time required to solve

problems of size 1







- In the above recursion tree, each level has cost *cn*.
- The top level has cost *cn*.
- The next level down has 2 subproblems, each contributing cost *cn*/2.
- The next level has 4 subproblems, each contributing cost *cn*/4.
- Each time we go down one level, the number of subproblems doubles but the cost per subproblem halves. Therefore, cost per level stays the same.
- The height of this recursion tree is log *n* and there are log *n* + 1 levels.

Total Running Time

- A tree for a problem size of 2^i has $\log 2^i + 1 = i + 1$ levels.
- The fully expanded tree recursion tree has log n+1 levels. When n=1 than 1 level log 1=0, so correct number of levels log n+1.
- Because we assume that the problem size is a power of 2, the next problem size up after 2ⁱ is 2ⁱ + 1. A tree for a problem size of 2ⁱ + 1 has one more level than the size-2ⁱ tree implying i + 2 levels.
- Since $\log 2^i + 1 = i + 2$, we are done with the inductive argument.
- Total cost is sum of costs at each level of the tree. Since we have log *n* +1 levels, each costing *cn*, the total cost is *cn* log n + *cn*.
- Ignore low-order term of *cn* and constant coeffcient *c*, and we have,
 Θ(*n* log *n*)

Total Running Time

- The fully expanded tree has Ig n +1 levels and
- each level contributes a total cost of cn.
- Therefore $T(n) = cn \log n + cn = \theta(n \log n)$

Growth of Functions

We look at input sizes large enough to

make only the order of growth of the

running time relevant.